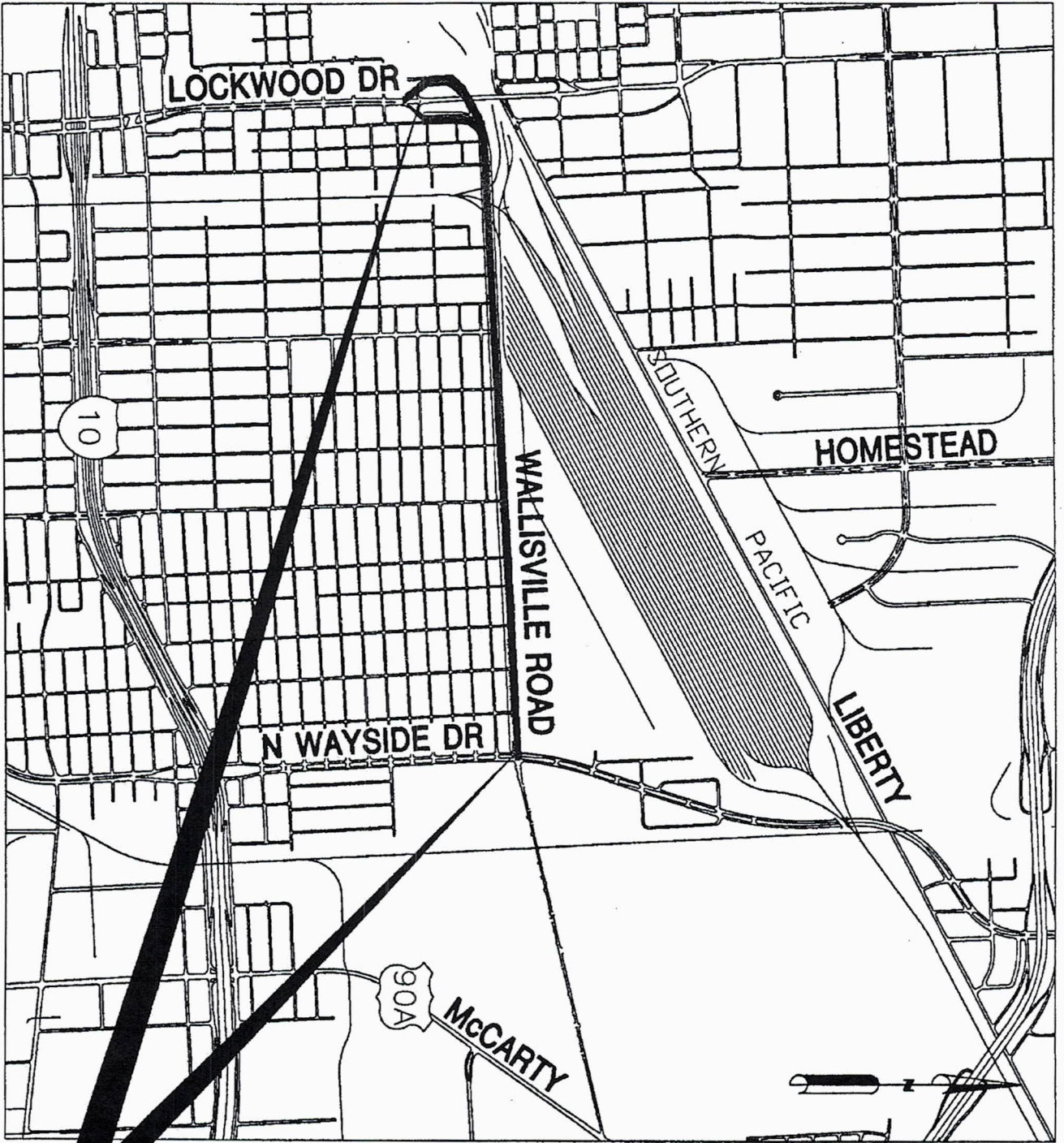


VICINITY MAP



**PROJECT
LOCATION**